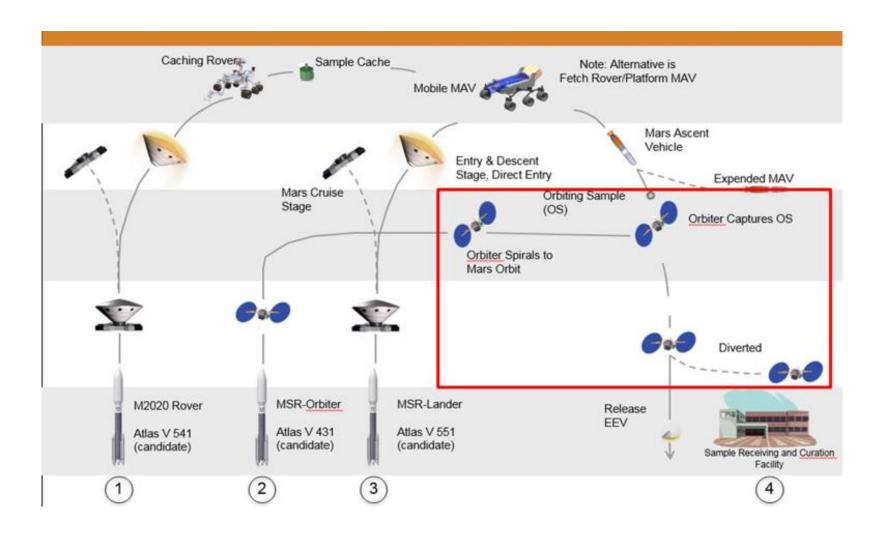


Testbeds and Technologies for Potential Mars Orbital Sample Capture and Manipulation

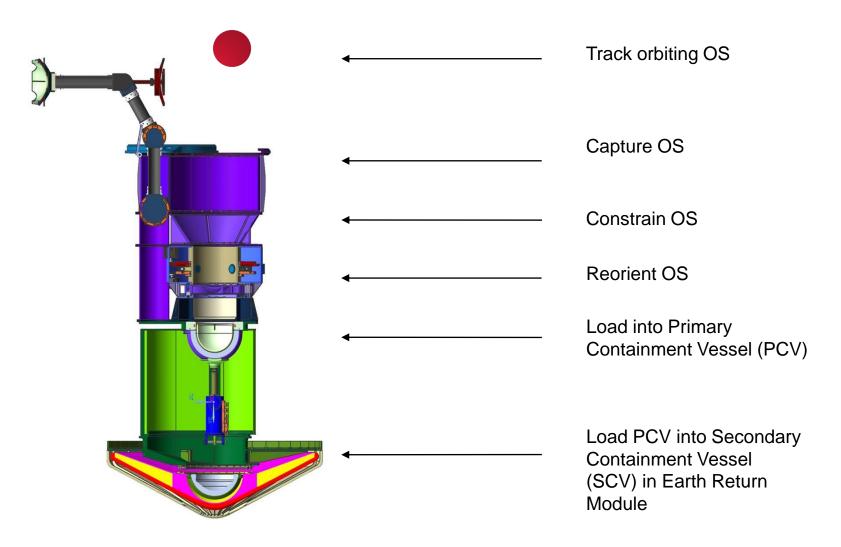
Brendan Chamberlain-Simon, Rudranarayan Mukherjee¹
Neil Abcouwer, Alex Brinkman, Marco Dolci, Blair Emmanuel, Johannes Gross, Lewis Jones, Junggon Kim, John Mayo, Preston Ohta, SaiAdiVishnu Sanigepalli, Vivian Shen, Russell Smith, Wyatt Ubellacker, Kristopher Wehage



Notional Mars Sample Return Architecture



Rendezvous Orientation & Capture System



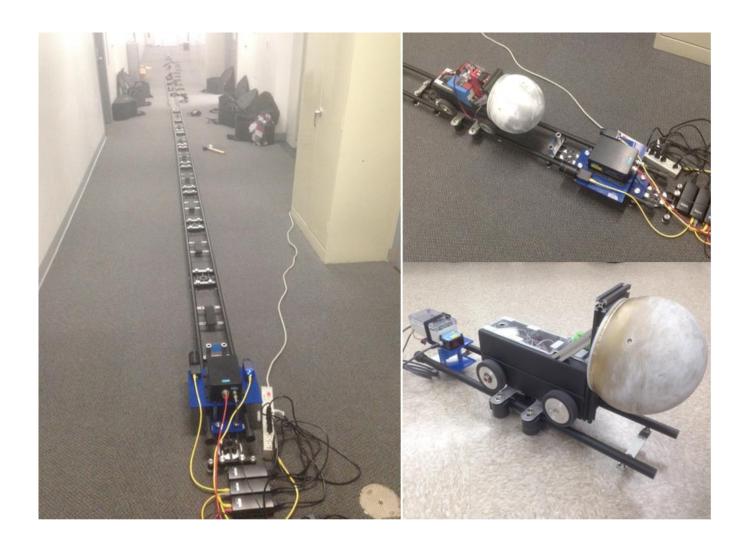
Overview of Testbeds

Standalone linear testbed for tracking OS

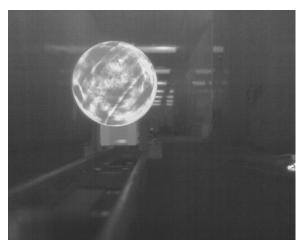
End-to-end testbed for ConOps 1 (Chimney Sweep)

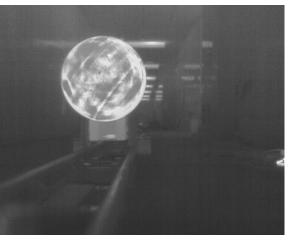
End-to-end testbed for ConOps 2 (MACARONE)

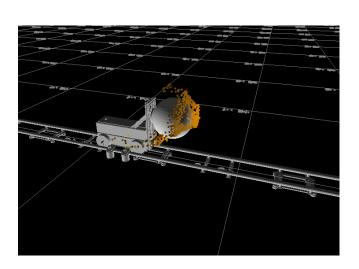
Testbed 1: Linear Stage



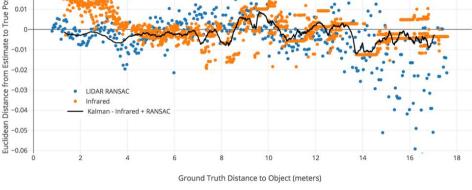
Linear Stage Results

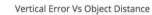


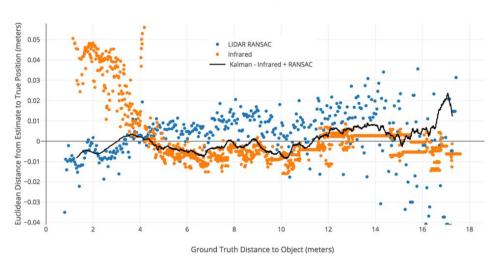




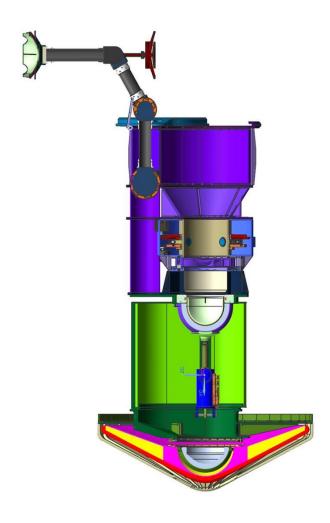
Horizontal Error Vs Object Distance



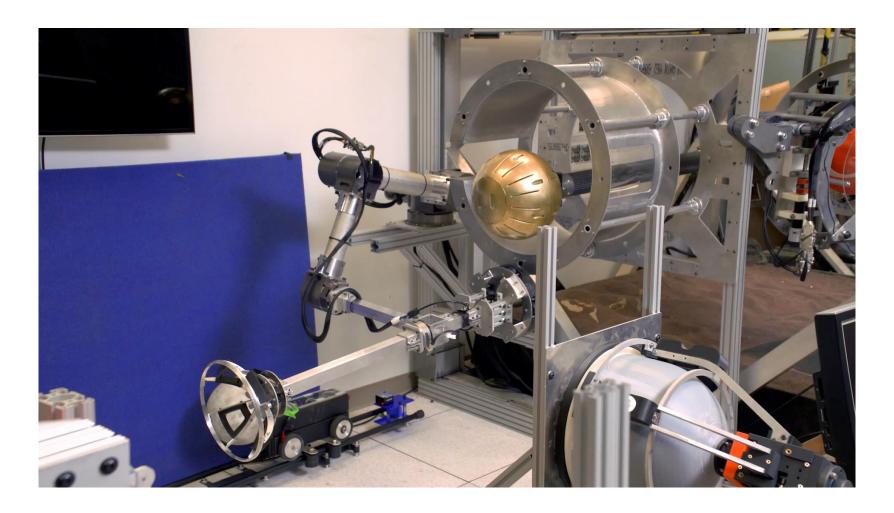




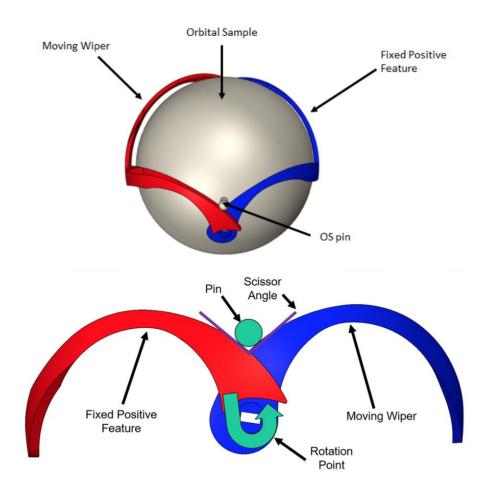
Testbed 2: Chimney Sweep



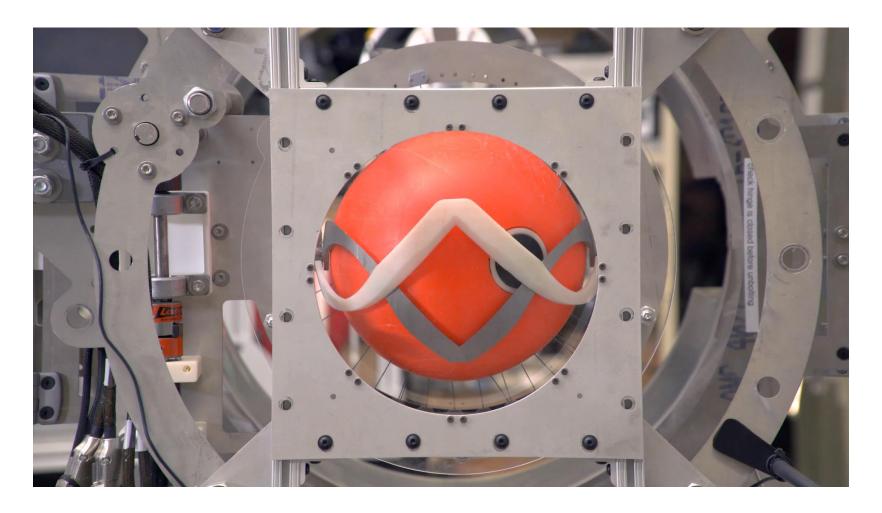
Capture & Constrain: Chimney Sweep



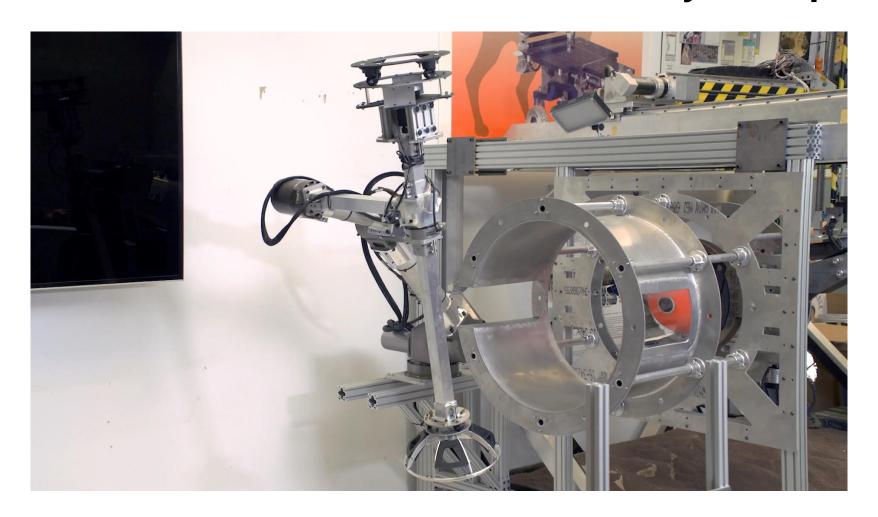
Reorientation Concept 1: Wiper



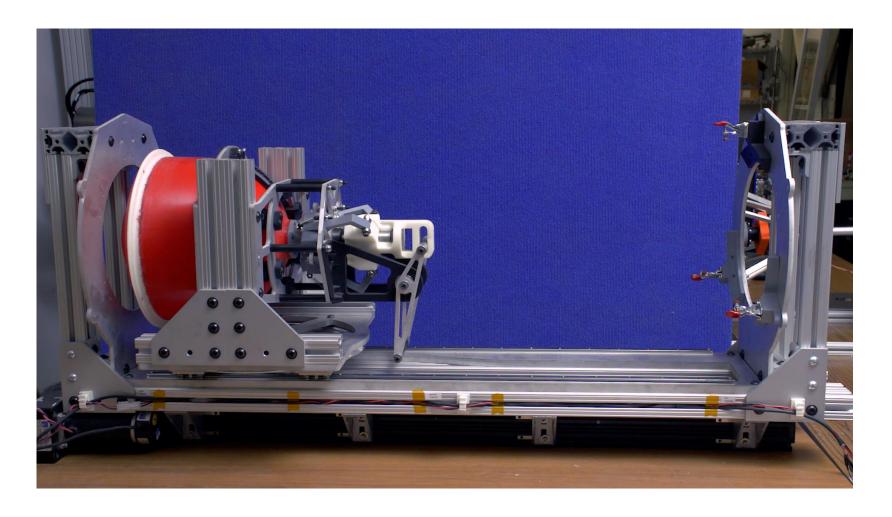
Reorientation: Chimney Sweep



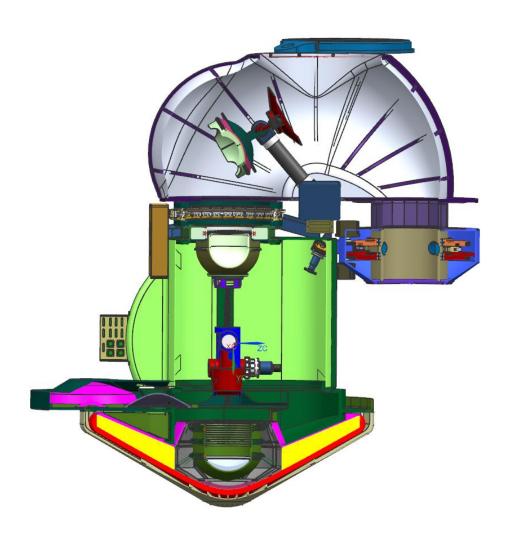
Transfer Oriented OS to PCV: Chimney Sweep



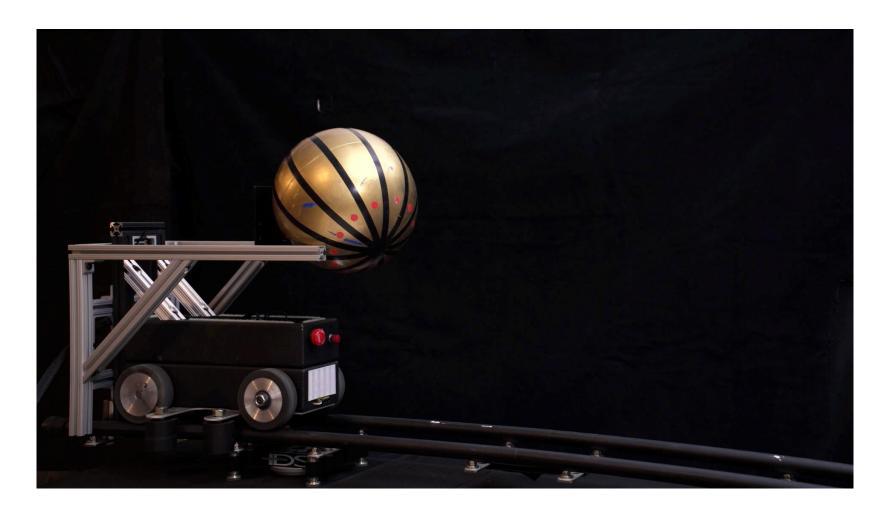
Load PCV into SCV: Chimney Sweep



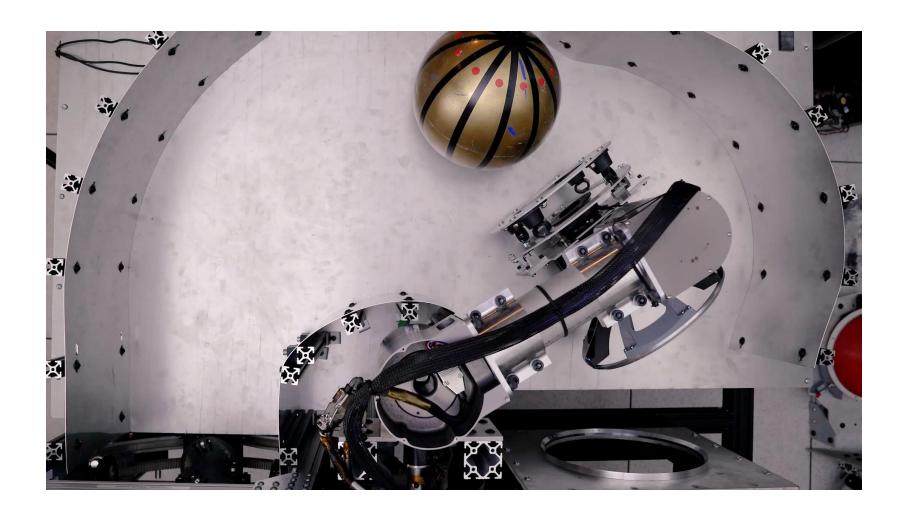
Testbed 3: MACARONE



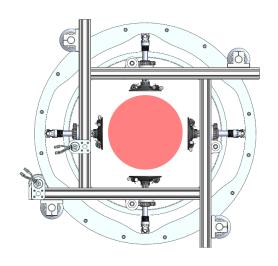
Capture: MACARONE

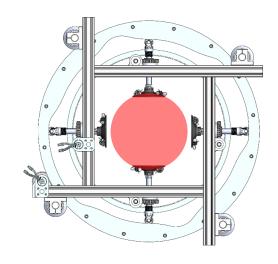


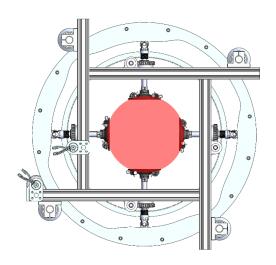
Constrain: MACARONE

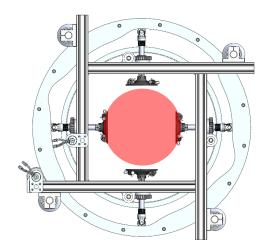


Reorientation Concept 2: Rubik's Cube Solver

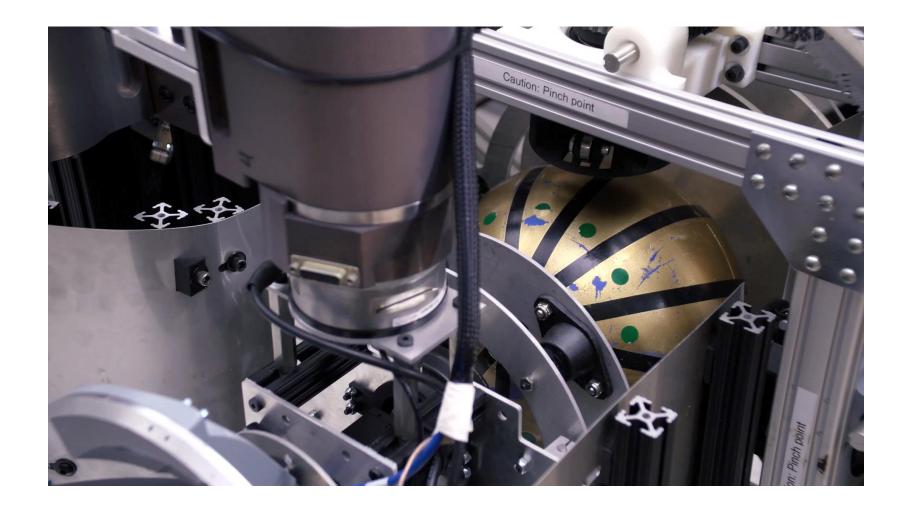




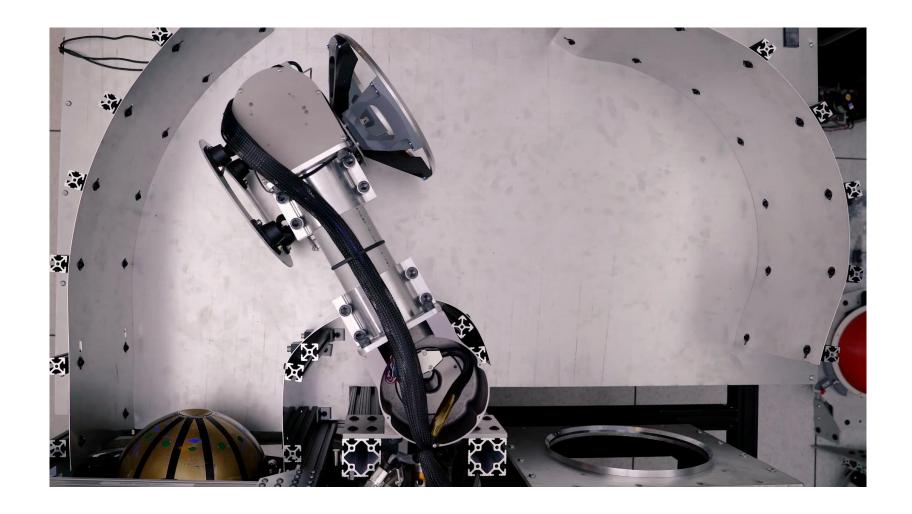




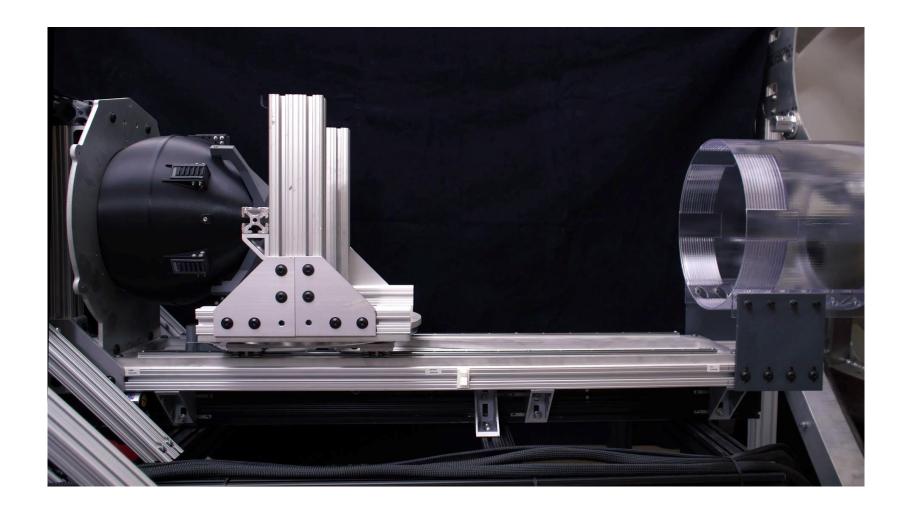
Reorientation: MACARONE



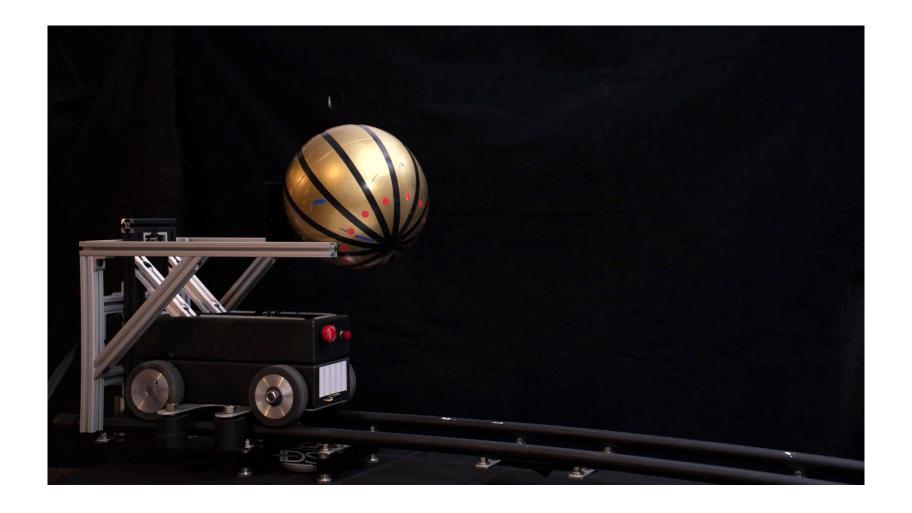
Transfer Oriented OS to PCV: MACARONE



Load PCV into SCV: MACARONE



End-to-end Testbed: MACARONE



Acknowledgements

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